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# A Safety Case + SPI Metric Approach for Autonomous Vehicle Safety

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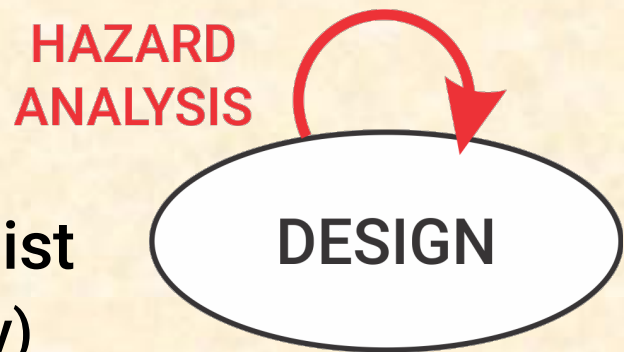
@PhilKoopman

- Multi-scale metric & feedback loops
  - Design hazard analysis
  - Operational risk mitigation
  - Lifecycle discovery of surprises
- Safety Performance Indicators (SPIs)
  - Beyond “vehicle acted unsafely”
  - Beyond real-time dynamic risk measurement
  - ...
  - It’s all about monitoring safety case validity

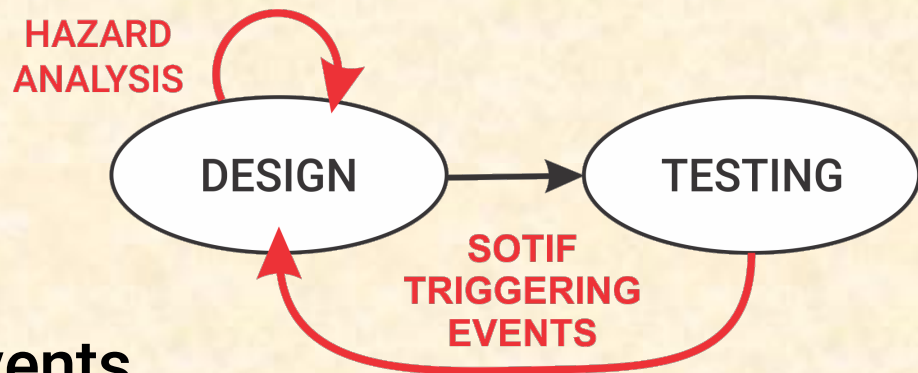


# Traditional Hazard Analysis

- Risk Analysis (e.g., start with HARA)
  - List all applicable hazards
  - Characterize the resultant risk
  - Mitigate risk as needed
  - Document all risks acceptably mitigated
- Use various techniques to create hazard list
  - Lessons learned (previous projects; industry)
  - Brainstorming & analysis techniques
    - HAZOP, STPA, ... bring your own favorite approach ...
- Limitation: unknown hazards
  - But, human is responsible for overall system safety

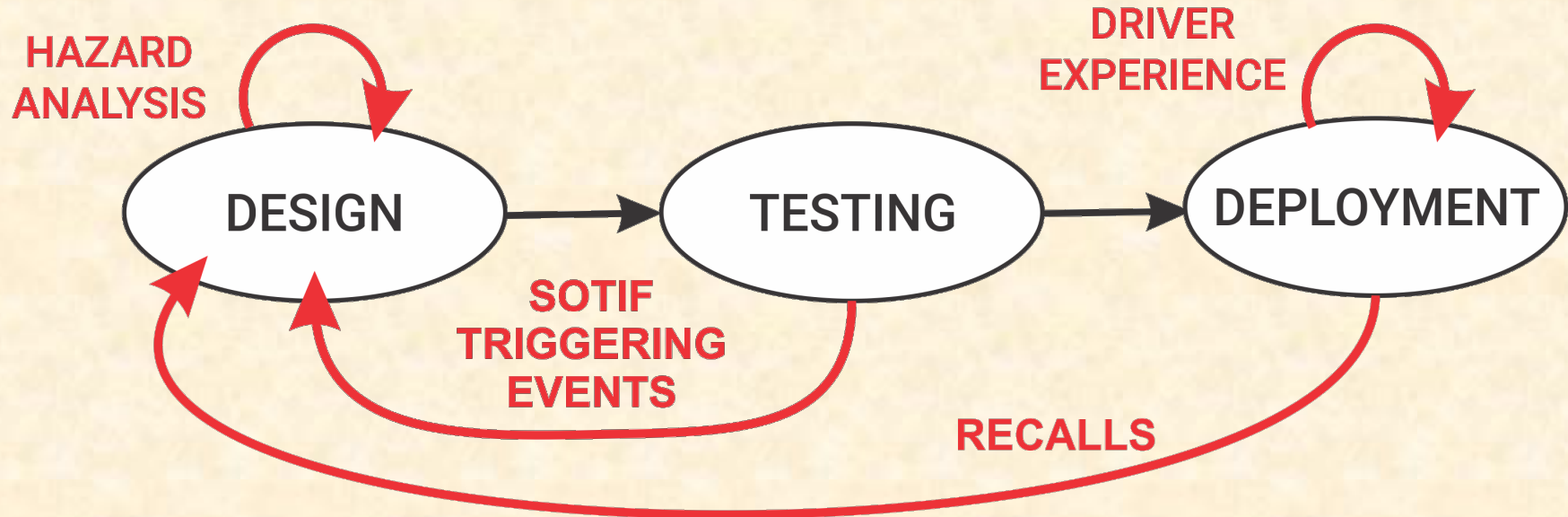


- Operating in the open world
  - All hazards aren't known
  - New hazards will appear
- Safety of the Intended Function (SOTIF)
  - Operate in the real world
  - Observe "triggering events"
  - Mitigate discovered hazards
  - Repeat
- Limitation: unseen triggering events
  - But, human is responsible for system safety



# Pre-Autonomy & ADAS Feedback Model

- Driver does dynamic risk mitigation
- Recalls for technical faults
  - Recalls are never supposed to happen



# Hazard Analysis for Full Autonomy

- Still an open world with unknowns & changes
  - But ... *no human driver responsible*

- Use Positive Trust Balance

- Engineering rigor
- Practicable validation
- Strong safety culture  
.... and ...
- Field feedback  
to handle surprises



- Good fit to UL 4600 → Safety Cases



# Safety Arguments (Safety Case)

- **Claim** – a property of the system

- “System avoids pedestrians”

- **Argument** – why this is true

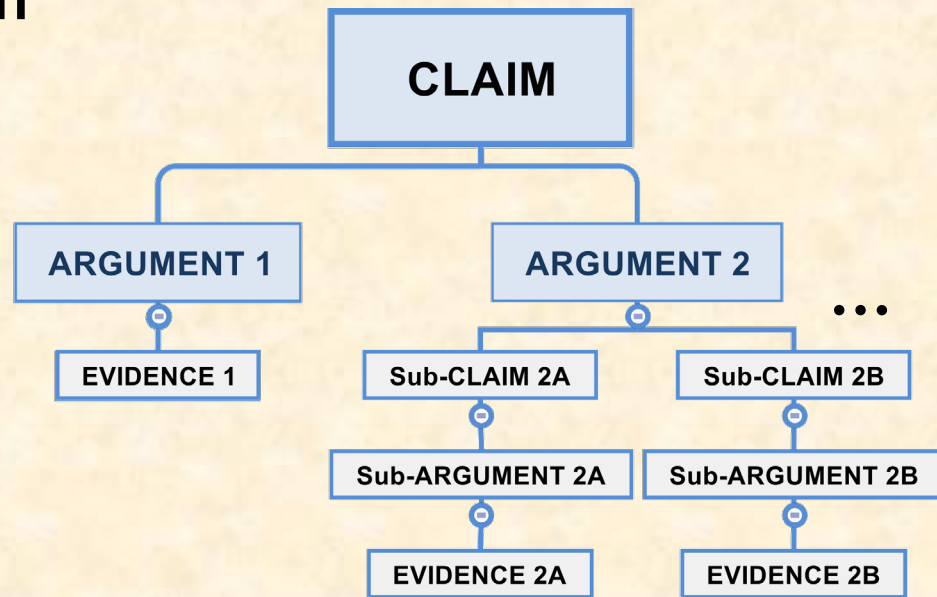
- “Detect & maneuver to avoid”

- **Evidence** – supports argument

- Tests, analysis, simulations, ...

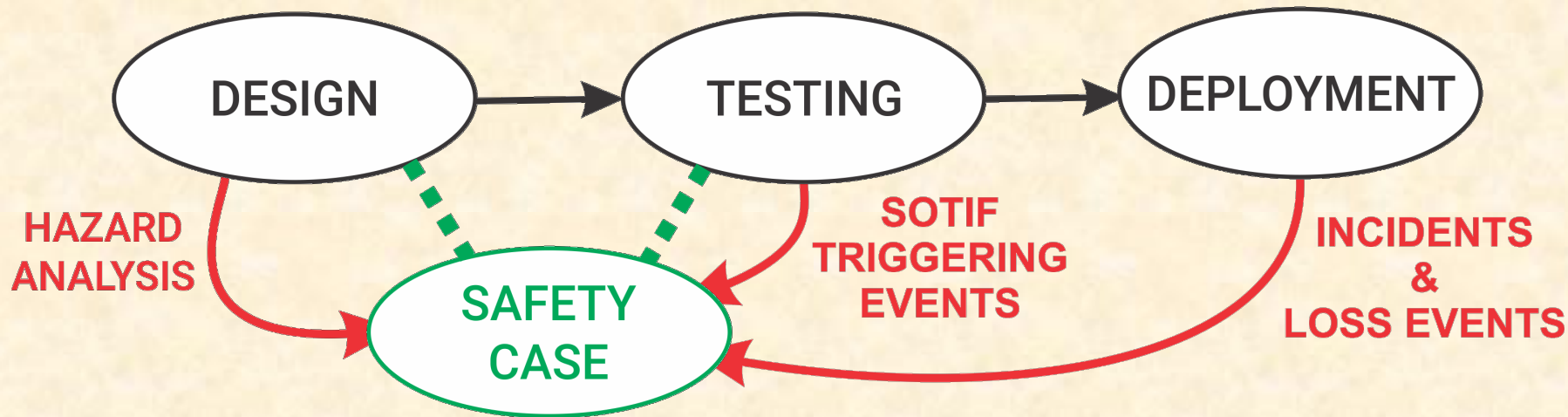
- **Sub-claims/arguments address complexity**

- “Detects pedestrians” // evidence
- “Maneuvers around detected pedestrians” // evidence
- “Stops if can’t maneuver” // evidence



# Default SDC Feedback Model

- Safety Case argues acceptable risk – without driver
  - Perhaps Positive Risk Balance (“safer than human”)
  - Update in response to incidents and loss events

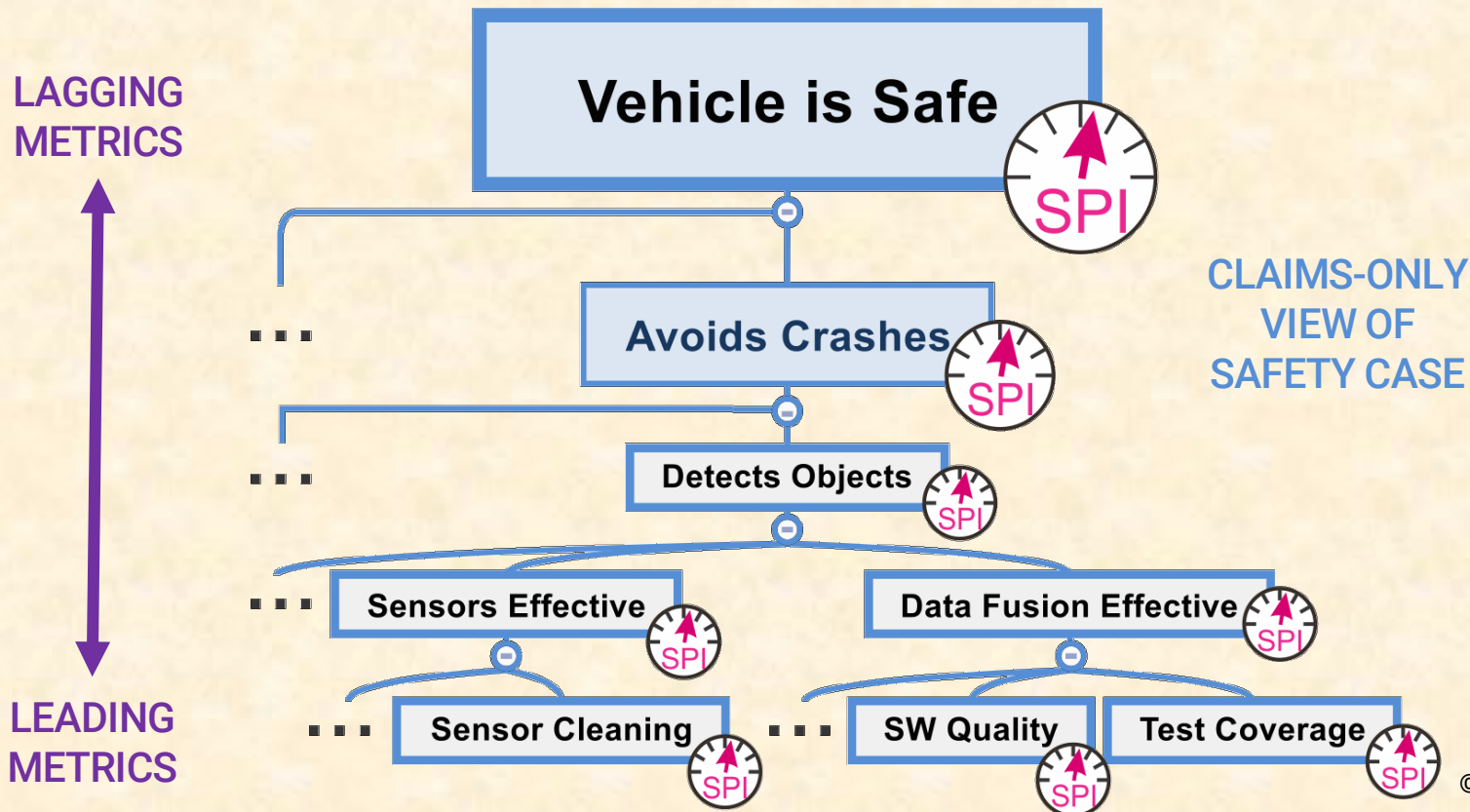


- But, deployment only yields lagging metrics



# Safety Performance Indicators (SPIs)

- SPIs monitor the validity of safety case claims



# Examples of SPIs

- “Acts dangerously” is only one dimension of SPIs
  - Violation rate of pedestrian buffer zones
  - Time spent too close per RSS following distance
- Components meet safety related requirements
  - False negative/positive detection rates
  - Correlated multi-sensor failure rates
- Design & Lifecycle considerations
  - Design process quality defect rates
  - Maintenance & inspection defect rates
- Is it relevant to safety? → Safety Case → SPIs

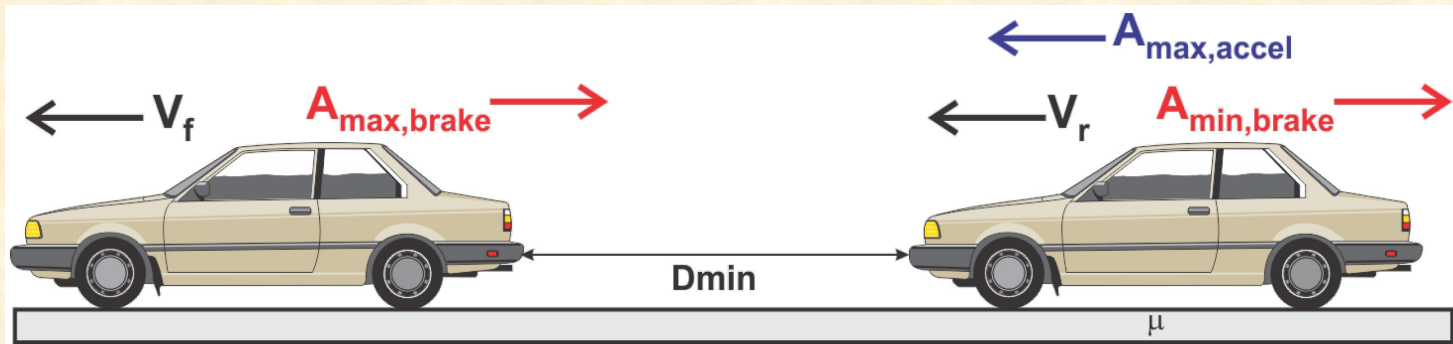


# KPI vs. SPI Contrast



- **Distance to object:**
  - KPI: average and variance of clearance
  - SPI: how often SDC violates safe clearance limit
- **Sensor effectiveness:**
  - KPI: detection rate, SNR per sensor
  - SPI: concurrent multi-sensor detection failure
  - SPI: loss of calibration
- **Pedestrian perception:**
  - KPI: accuracy, precision, recall
  - SPI: false negative more than  $\langle k \rangle$  consecutive frames
  - SPI: systematic under-performance on sub-classes

## ■ Responsibility-Sensitive Safety (RSS) Scenario:



- Safety monitor: increase distance if too close in case of panic stop
- KPI: best effort separation given driving conditions
- SPIs: situation more dangerous than expected (e.g., ODD issues)
  - Spent more time in too-dense traffic than expected
  - Lead/own vehicle brake violate expectations
  - Other vehicles panic brake more often than assumed

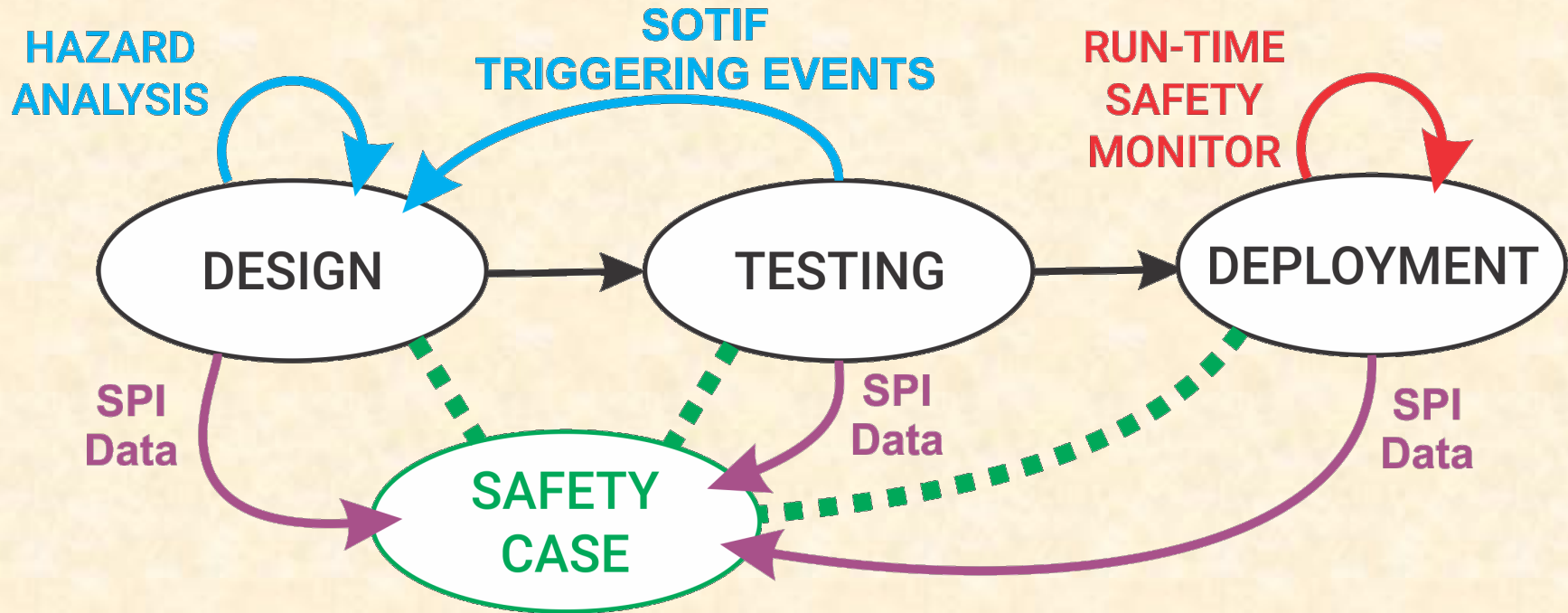
- SPI measures validity of a safety case claim
  - ➔ a SPI value violation means safety case is invalid
- Root cause analysis might reveal:
  - Design process execution defect
  - Design defect
  - Hazard analysis gap
  - SOTIF analysis gap
  - Training data bias
  - Evidence gap, or defect
  - Assumption error





# SPI-Based Feedback Approach

- Safety Case argues acceptable risk
  - SPIs monitor validity of safety case





- Monitoring incidents is only part of feedback
- Removing human means mitigating surprise
  - Tactical: run-time safety monitoring
  - Strategic: run-time SPI monitoring
- SPIs provide feedback on:
  - Design quality & process maturity
  - Testing coverage
  - Lifecycle procedure execution
- SPIs: you are as safe as you think you are
  - Field feedback is key to SPI success

